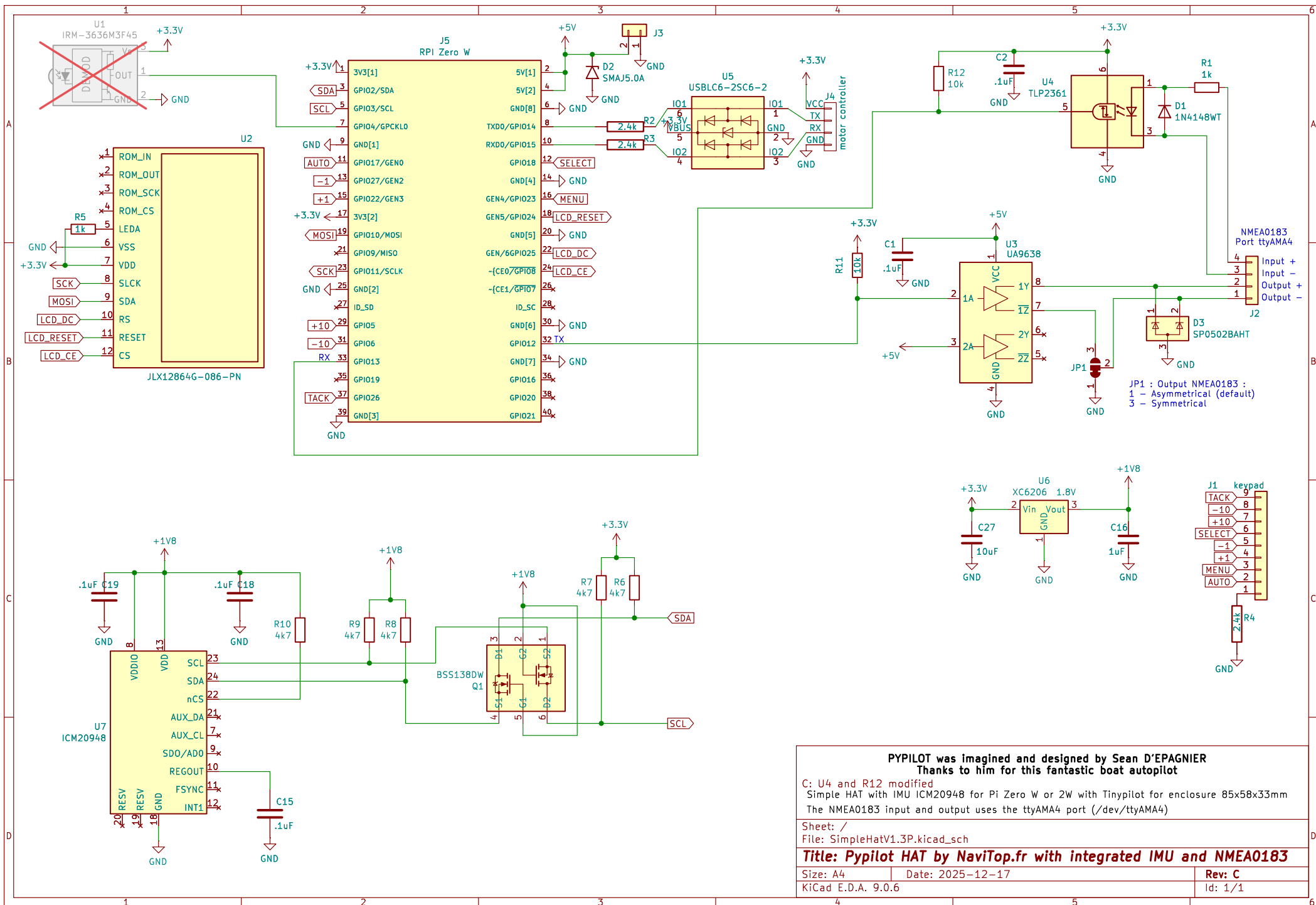




PYPILOT was imagined and designed by Sean D'EPAGNIER
Thanks to him for this fantastic boat autopilot

C: U4 and R12 modified
Simple HAT with IMU ICM20948 for Pi Zero W or 2W with Tinpilot for enclosure 85x58x33mm
The NMEA0183 input and output uses the ttyAMA4 port (/dev/ttyAMA4)

Sheet: /
File: SimpleHatV1.3P.kicad_sch

Title: Pypilot HAT by NaviTop.fr with integrated IMU and NMEA0183

Size: A4	Date: 2025-12-17	Rev: C
KiCad E.D.A. 9.0.6		Id: 1/1